INTERNATIONAL APPLICATION PUBLISHED UNDER THE PATENT COOPERATION TREATY (PCT)

(54) Title: RF POWER AMPLIFIER WITH LINEARIZATTION
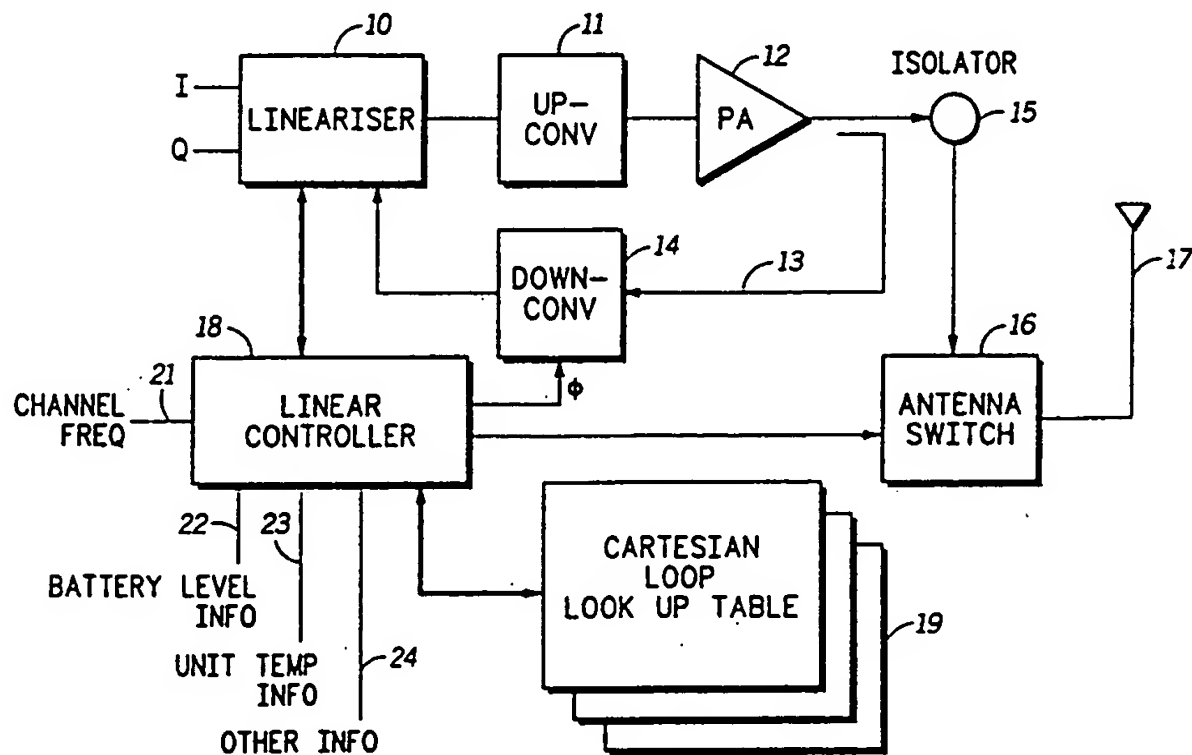
LINEARISER BLOCK DIAGRAM

(57) Abstract

A radio transmitter is provided comprising: a power amplifier (12); linearizing means (10) for maintaining linearity in the power amplifier; and feedback means (13) for feeding a signal from an output of the power amplifier to the linearizing means for maintaining linearity, said amplifier, linearizing means and feedback means forming a loop having adjustable loop linearization parameters (for example phase and gain): a look-up table (19) for storing predetermined loop linearization parameters; and control means having an operating condition input, said control means being coupled to the look-up table and the loop for selecting a loop linearization parameter in response to a transmit control signal according to an operating condition input, such as battery level or temperature, to the central means at the time of receipt of the transmit control signal. The invention also provides an adjacent channel receiver for monitoring the linearization and other factors.

RF Power Amplifier with Linearization

Field of the Invention

5   This invention relates to a radio frequency power
amplifier employing a linearization technique.

Background of the Invention

10   Future mobile radio systems will be required to improve
their spectral efficiency beyond that which currently exists
today. This will mean that modulation schemes in which the
information is carried in both the transmitted signal
amplitude and phase will increasingly become required. In
15   order to conserve spectrum and to coexist with current radio
systems the transmitters using these complex modulations will
have to be linear. For example adjacent channel interference
levels of > -60dBc in a 25kHz channelisation may be required.

20   ## Summary of the Prior Art

One technique to achieve such power amplifier linearity
performance is Cartesian feedback. This technique has become
popular as it lends itself to integration on IC's.
25   The requirement for linearity (determined by adjacent
channel interference limits) and maximum power efficiency,
means that the power amplifier will have to operate as close
to the gain compression (clip) point as possible, but still
retain required level of linearity.
30   A known technique to measure and adjust for maximum
phase margin of the closed loop system and to identify the
clip point of the amplifier uses an appropriate training
sequence. Gain compression is detected by an increase in the
magnitude of the Cartesian loop error signal above a given
35   threshold. At this point the drive level control circuits
are set appropriately and linear operation is assured - i.e.
input signal is backed off.
The above technique is only suitable in future radio
products where time is available for training prior to each

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transmission. Time delays generally required to implement training are in the order of milliseconds. To allow this linearization technique to be implemented in systems where no training time is allocated, an alternative approach is
5 required.

In addition to achieving linearity through training, there is a need for improved methods of maintaining linearity.

10 **Summary of the Invention**

According to the invention, there is provided a radio transmitter comprising: a power amplifier; linearizing means for compensating for non-linearity in the power amplifier;
15 and feedback means for feeding a signal from an output of the power amplifier to the linearizing means for maintaining linearity, said amplifier, linearizing means and feedback means forming a loop having adjustable loop linearization parameters; a look-up table for storing predetermined loop
20 linearization parameters; and control means having an operating condition input, said control means being coupled to the look-up table and the loop for selecting a loop linearization parameter in response to a transmit control signal according to an operating condition input to the
25 central means at the time of receipt of the transmit control signal.

The loop linearization parameters may be phase and/or gain parameters.

The operating condition input may be channel frequency,
30 battery level, temperature or other information. A separate table may be stored for different values for each of these parameters. Thus, when operating at half the battery level, a table may be selected relating to that battery level.

There is preferably a temperature input receiving a
35 signal from a temperature sensor.

The tables preferably have settings for both phase and gain parameters.

In a particularly preferred feature of the invention, the look-up table is updated by measuring the actual loop

linearization parameter, selecting an improved linearization
parameter and writing the improved parameter into the look-up
table. In this manner, the accuracy of the look-up tables
can be maintained with time. Moreover, by continuously

5 updating the look-up tables, it is not necessary to store as
extensive a range of linearization parameters for different
operating conditions.

A phase setting is particularly sensitive to changes in
operating conditions and the look-up tables may contain more

10 phase parameter information than gain parameter information.
In particular, if the phase margin can always be maintained
at a maximum level, reduced adjacent channel splatter is
observed.

For continuously measuring the phase and/or gain or

15 other parameter of the loop, it is particularly preferred
that receiver means are provided tuned to an adjacent
transmitter channel for measuring modulation on the adjacent
channel.

The adjacent channel receiver means may take the form of

20 an adjacent channel receiver coupled to the output of the
power amplifier and dedicated to the purpose of measuring the
transmitter adjacent channel power. Alternatively, the
adjacent channel receiver means may take the form of a
receiver switchable between a first receive frequency which

25 is separated from the frequency of the signal from the power
amplifier by a duplex separation frequency and a second
frequency which represents the frequency of a channel
adjacent to that of the signal from the power amplifier.

In the latter of the above embodiments of adjacent

30 channel receiver means, it is preferred that control means
are provided for switching the receiver between a receive
frequency on a receive timeslot and an adjacent channel
frequency on a transmit timeslot and back to the receive
frequency on a subsequent receive timeslot.

35   Attenuator means may be provided switchable into a path
between the power amplifier and the adjacent channel receiver
for attenuating the signal from the power amplifier to the
adjacent channel receiver during transmission and for passing

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an unattenuated signal from an antenna during a receive mode
of operation.

Brief Description of the Drawings

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Fig. 1 shows a block diagram of a radio transmitter with
power amplifier and linearizer in accordance with a first
embodiment of the invention.

Fig. 2 shows a block diagram of a radio transmitter with
10   power amplifier and linearizer in accordance with a second
embodiment of the invention.

Fig. 3 shows switched attenuator circuit for switching
into the circuit of Fig. 2 at point (b).

Fig. 4 shows a TDMA timing format in which the invention
15   may be employed.

Detailed Descriptions of the Preferred Embodiments

Referring to Fig. 1, there is shown a radio transmitter
20   comprising a linearizer 10, an upconverter 11, a power
amplifier 12, a feedback loop 13, and a downconverter 14.
The output of the power amplifier 12 is connected via an
isolator 15 and an antenna switch 16 to an antenna 17. A
linear controller 18 is provided connected to the linearizer
25   10, the downconverter 14 and the antenna switch 16.
Connected to the linear controller 18 is a series of look-up
tables in memory 19. The linear controller 18 has a number
of inputs of which a channel/frequency input 21, a battery
level input 22, a unit temperature input 23 and other
30   information inputs 24 are shown.

On accepting a request for transmission from a push-to-
talk (PTT) switch (not shown) or otherwise, the transmitter
power amplifier 12 is turned on. The various operating
parameter inputs 21, 22 and 23 are measured by the controller
35   18 and a look-up table 19 is selected for the measured
conditions. Thus, for a particular channel, battery level and
measured temperature (as indicated by a temperature sensor),
predetermined gain and phase settings will be downloaded from
the look-up table 19.

5

The linearizer phase shift and drive level attenuator
settings, which are described in more detail in the paper
"Transmitter Linearization using Cartesian Feedback for
Linear TDMA Modulation" by M Johansson and T Mattsson 1991,
5   IEEE are set in the downconverter 14 and the linearizer 10
respectively by the linear controller 18 depending on the
values read from the look-up table 19. The antenna switch 16
is at this point operated using an appropriately controlled
ramp signal, having a raised cosine profile, to avoid excess
10   splatter to adjacent channels. Transmission of the
information (data or voice) defined by I and Q samples input
to the linearizer 10 now takes place in a stable linear
operation.

The values in the look-up table 19 are set in the
15   factory by extensive testing at different temperatures
battery levels, etc.

In a more preferred embodiment of the invention, the
values in the look-up table are updated as the radio is used.

For a given transmission request, the loop phase and
20   gain parameters read from the look-up table 19 are those set
in the look-up table from a previous transmission on the
channel in question at the battery level and temperature in
question. When these values have been loaded into the
linearizer 10 and transmission begins, a comparison is made
25   between the I and Q values input and those received on the
feedback loop 13 from the downconverter 14. Based on a
comparison of these values, a decision is made as to the need
for updating the loop phase and gain parameters. If, for
example, the phase margin has decreased, a new phase setting
30   is calculated to increase the phase margin for the loop.
This new phase setting is now written into the particular
location in the look-up table 19 for the current channel,
battery level and temperature settings and replaces the
previously existing value. The new value will be used next
35   time a transmission is requested on that channel at that
battery level and at that temperature.

An assumption is made that changes in loop phase and
gain characteristics due to battery voltage and temperature
are independent of one another. This allows separate look-up

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tables to be used for different battery voltage settings and
temperature settings. It is found that this is a workable
assumption, however, more extensive look-up tables can be
stored for particular battery level and temperature pairs.
5 The memory 19 can be arranged in other formats.
Interpollation may be carried out between values, e.g. values
for measurements at two temperature when the temperature
sensor senses an intermediate temperature.

To allow for the linearizer adjustment, the ramp signal
10 to the antenna switch is delayed by an appropriate amount Δt;
this is to compensate for the look-up table access time and
downloaded to the linearizer circuitry. This delay is
assumed to be minimal in comparison with the ramp time of the
antenna switch. Therefore when the antenna is connected to
15 the power amplifier output, the power amplifier is operating
at the correct level to ensure compliance with required
interference specifications.

As an alternative to sensing of loop gain and phase
settings and refreshing the look-up table entries after each
20 transmission, a retraining sequence can be input to the
linearizer 10 and transmitted out of the antenna 17, or into
a load as described in co pending UK patent application
.... entitled "Radio Transmitter with Linearization
Training Sequence" file don the same date as the present
25 application, or transmitted into an adjacent channel receiver
as is described below.

The sensing of loop gain and phase settings and
refreshing of the look-up table entries after each
transmission does not incur a time penalty and allows the
30 transmitter to be available at all times. The values in the
tables can be refreshed when a measured value deviates from a
stored value by more than the predetermined amount, or they
can be refreshed at regular intervals.

If retraining is used, this can be implemented by
35 refreshing the look-up table entries on every power-up of the
radio, by refreshing the look-up table entries at fixed
intervals of operation in terms of absolute time or
transmission time, or refreshing the look-up table entries at
intervals dictated by radio transmitter conditions.

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Loop phase and drive level settings are monitored and
adjusted during transmission to take into account changing
device characteristics and the linearized power amplifier is
optimized for both stability and efficiency. The transmitter
5   efficiency is maximized by operating the power amplifier as
close to its gain compression point as possible, as described
in US Patent Application No. 606679 of Motorola Inc, annexed
hereto as "Annex 1" The transmitter, however, is restricted
by the amount of adjacent channel interference it should be
10   allowed to generate. For maximum efficiency the transmitter
must operate as close to the adjacent channel interference
limit as possible. It would be desirable to provide an
improved means for performing a "clip detect" operation to
find the optimum setting of loop gain for the feedback
15   network.

An arrangement is shown in Fig. 2 which meets the above
need and comprises a number of elements already described
with reference to Fig. 1. In Fig. 2, there is shown a
microprocessor 30 which controls the gain (A) and phase (ϕ)
20   of the feedback loop. In Fig. 2, a phase adjuster 31 is
shown separate to the linearizer 10, as is a feedback phase
detector 32. It will be appreciated that these elements are
present in the circuit of Fig. 1, but are merely encompassed
within the linearizer block 10 of Fig. 1.

25   In addition to the above elements, the circuit of Fig. 2
has an adjacent channel receiver 33, or in a further
embodiment, as an alternative to adjacent channel receiver
33, a subscriber receiver 34 is provided with a control input
from microprocessor 30 for changing the receive frequency of
30   the subscriber receiver 34 from a receive mode (for receiving
voice/data from the antenna 17) to an adjacent channel
receive mode for measuring adjacent channel receive power.

Referring to the first of these alternative embodiments,
the adjacent channel receiver 33 is connected to the output
35   of the power amplifier 12 and comprises an attenuator, a
downconverter to a suitable IF frequency, a mixer which taps
a signal from a main synthesizer for the radio, an IF filter,
an attenuator, a rectifier and means for measuring voltage
across the rectifier. A ceramic filter is suitable for the

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IF filter. This ceramic filter is a 25 KHz bandpass filter
tuned to a frequency 25KHz offset from the IF signal for the
corresponding transmit channel.

          In the second embodiment shown in Fig. 2 in which the
5   subscriber receiver 34 changes between a receive mode and an
adjacent channel receive mode, operation will be described
with reference to a TDMA system having 60 millisecond frames
divided into 4 timeslots of 15 milliseconds each as shown in
Fig. 4. A transmit frame is always offset from a receive
10   frame and vice versa. A channel pair may comprise the first
timeslot of the transmit frame and the first timeslot of the
receive frame or the second timeslot of the transmit frame
and the second timeslot of the receive frame etc. There will
always be about 15 milliseconds between the end of a transmit
15   timeslot and the beginning of a receive timeslot. This
provides ample time for the microprocessor 30 to provide a
control signal to the synthesizer of the subscriber receiver
34 to cause a receive frequency change equal to the duplex
frequency separation between the transmission receive
20   frequencies less (or in addition to) an amount equal to the
channel spacing. Where the duplex frequency separation is
10MHz, and the channel separation is 25 KHz, the signal from
the microprocessor causes the receiver 34 to change its
receive frequency through 9.975 MHz or 10.025 MHz. After a
25   receive frame, the receiver 34 changes its frequency to be
adjacent that of the signal being transmitted from power
amplifier 12 in a transmit frame and, after transmission, it
switches back to its appropriate receive frequency for
receiving the next timeslot from the antenna 17.
30   While the adjacent channel receiver 33 or the re-tuned
subscriber receiver 34 is tuned to the adjacent channel, it
is able to measure the power on the adjacent channel. If the
level of signal on the adjacent channel exceeds a threshold,
for example a threshold of 60 or 63 dB below the output level
35   of the power amplifier 12, this is an indication of onset of
clipping in the power amplifier 12 and an indication that it
is necessary to back off the gain of the power amplifier 12.
Thus, the adjacent channel receiver 33 or the subscriber
receiver 34 provides a signal to the microprocessor 30 from

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which, if onset of clipping is detected, controls the
linearizer 10 to reduce the gain A.

   As a result, with a real-time knowledge of the splatter
to adjacent channel power, backing off made to the drive
5   level to the power amplifier can be minimised at all times
ensuring true optimum operating efficiency. In addition, the
arrangement ensures a predetermined maximum splatter into the
adjacent channel at all times.

   On detecting of clipping and backing off of the power
10 amplifier, the new value for the loop gain (a) can be loaded
into the look-up tables of Fig. 1.

   The adjacent channel receiver of 33 or subscriber
receiver 34 can be used for detecting "clip" during a
training sequence such as that described in US Patent No.
15 5066923 of Motorola Inc. During the training sequence, the
energy of the power amplifier is diverted into the adjacent
channel receiver 33 or the subscriber receiver 34 by
isolation of the antenna 17 using the antenna switch 16.
This allows the energy to be directed away from the antenna
20 ensuring "off-air" training and no on-air adjacent channel
splatter. It is proposed that this transmit energy whilst
training is diverted into the appropriate receiver by the
microprocessor 30 controlling the antenna switch 16. This
can be achieved by:

25   (1) coupling of some of the feedback signal power into a
separate receiver tuned to the adjacent channel or

        (2) short circuiting the antenna switch into the
subscriber unit receiver and switching the down-converter
local oscillator frequency by the duplex separation frequency
30 plus or minus the channel bandwidth, therefore allowing the
standard receiver to perform a received signal strength
indication on the adjacent transmit channel.

   In the case of a short circuited implementation,
suitable attenuation of the transmitter power is required to
35 avoid over driving the receiver. This is implemented by
appropriate switching of receiver paths 40 and 41 as shown in
Fig. 3. Receiver path 40 provides a path from the antenna 17
to the receiver 34. Adjacent channel receive path 41
provides a path in the case of routing of the signal from the

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power amplifier 12 to the receiver 34. The circuit comprises three pin diode switches 16, 43 and 44 under control of the microprocessor 30. An attenuator 45 is provided in the adjacent channel receive path 41, having a suitable value to
5   avoid overdriving the receiver circuitry. The operation is as follows. Simultaneously with the switching of the antenna switch 16 by the microprocessor controller 30, the controller 30 causes pin diode switches 43 and 44 to switch from path 40 to path 41, thus switching attenuator 45 into the path to
10 protect the receiver. The timing can be arranged such that attenuator 45 is always switched into the path before antenna switch 16 switches

        The measurement of the adjacent channel power in the adjacent channel receiver can be accomplished by any of the
15 standard methods available. One of which is to use an FFT of the received signal, and then processing this data to obtain a measurement of the adjacent channel power. The generation of the transmit spectrum has the advantage over the previously described method of using the a separate adjacent
20 channel receiver for measuring the adjacent channel power as it is able to monitor both adjacent channels simultaneously.

        The invention also allows a method of real-time monitoring of the phase shift around the feedback loop, thus allowing the loop phase to be adjusted whenever required,
25 ensuring stability at all times. This technique can be utilised to reduce the phase margin normally designed into such feedback systems, therefore creating an opportunity to increase the loop gain and consequently improve the intermodulation performance that is attainable by significant
30 amount.

        It is proposed that some of the feed-back signal is routed into a phase detector, which then transmits the phase information of the feed-back signal to the microprocessor. This phase measurement can then be compared against the phase
35 of the transmitted signal (which is also measured). Any transmit data is suitable for use with this phase comparison. It is suggested that for continuous operation mode within current TDMA frame structures, that measuring the phase shift of the synchronisation word is a good option.

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Phase shift measurement during the synchronisation word
is carried out at the beginning of a timeslot when the
synchronisation work is transmitted in terms of predetermined
I and Q samples being input to linearizer 10. These

5   predetermined I and Q samples can be used for comparison with
the corresponding samples measured by downconverter 14.
Thus, the phase shift measurement is carried out during
transmission of the synchronisation word.

The overall arrangement described provides the

10   advantages of:

(1) providing a method of "clip detection" by measuring
the splattered power transmitted into the adjacent channel as
part of a training process or as a real-time measurement of
the intermodulation performance of the loop:

15   (2) providing an alternative method of measuring the
phase shift around the feedback loop during continuous
operation and during a training process and

(3) maximising the operating efficiency of the power
amplifier by operating as close as possible to its saturation

20   level whilst maintaining a satisfactory intermodulation ratio
performance.

Instead of using Cartesian feedback, predistortion
feedback can be used as described in the paper "Linear
Amplification Technique for Digital Mark Communications" by

25   Yoshinori Nagata 1989 IEEE. In this case parameters other
than gain and phase will be stored in the look-up table.
Instead, I and Q sample predistortion factors or parameters
will be stored.

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CLAIMS

1.   A radio transmitter comprising:

a power amplifier;

5   linearizing means for compensating for non-linearity in the power amplifier; and

feedback means for feeding a signal from an output of the power amplifier to the linearizing means for maintaining linearity, said amplifier, linearizing means and feedback
10   means forming a loop having adjustable loop linearization parameters;

a look-up table for storing predetermined loop linearization parameters;

and control means having an operating condition input,
15   said control means being coupled to the look-up table and the loop for selecting a loop linearization parameter in response to a transmit control signal according to an operating condition input to the central means at the time of receipt of the transmit control signal.

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2.   A radio transmitter according to claim 1, wherein the operating condition input is coupled to sensing means for sensing at least one of frequency, battery level and temperature.

25

3.   A radio transmitter according to claim 1 or 2 further comprising means for monitoring the actual loop linearization parameter, means for selecting an improved linearization parameter and means for writing the improved parameter into
30   the look-up table.

4.   A radio transmitter according to claim 3, wherein the means for monitoring the loop linearization parameter comprises receiver means tuned to an adjacent transmit
35   channel for measuring signals on the adjacent transmit channel originating from the power amplifier.

5.   A radio according to claim 4, wherein the receiver means comprise a receiver switchable between a first receive

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frequency which is separated from the frequency of the signal
from the power amplifier by a duplex separation frequency and
a second frequency which represents the frequency of a
channel adjacent that of the signal from the power amplifier.

5

6.   A radio according to claim 5 further comprising control
means for switching the receiver between a receive frequency
on a receive timeslot and an adjacent channel frequency on a
transmit timeslot and back to the receive frequency on a
10   subsequent receive timeslot.

7.   A radio according to claim 5 or 6 further comprising
attenuator means switchable into a path between the power
amplifier and the receiver for attenuating the signal from
15   the power amplifier to the receiver during transmission and
for passing an unattenuated signal from the antenna during a
receive mode of operation.

8.   A radio according to claim 2 further comprising means
20   for inputting a training sequence into the linearizing means,
monitoring the actual loop linearization parameter in
response to the training sequence and selecting an improved
linearization parameter in response to the monitoring.

25   9.   A radio transmitter circuit comprising:
       a power amplifier coupled to an antenna for transmission
of radio signals on a transmit channel;
       linearizer means for compensating for non-linearity in
the power amplifier; characterized by
30   adjacent channel receiving means tuned to a channel
adjacent the transmit channel for measuring signals from the
power amplifier appearing on the adjacent channel and means
for adjusting the linearizer means in response to signals
measured on the adjacent channel.
35

10.   A radio according to claim 9 further comprising means
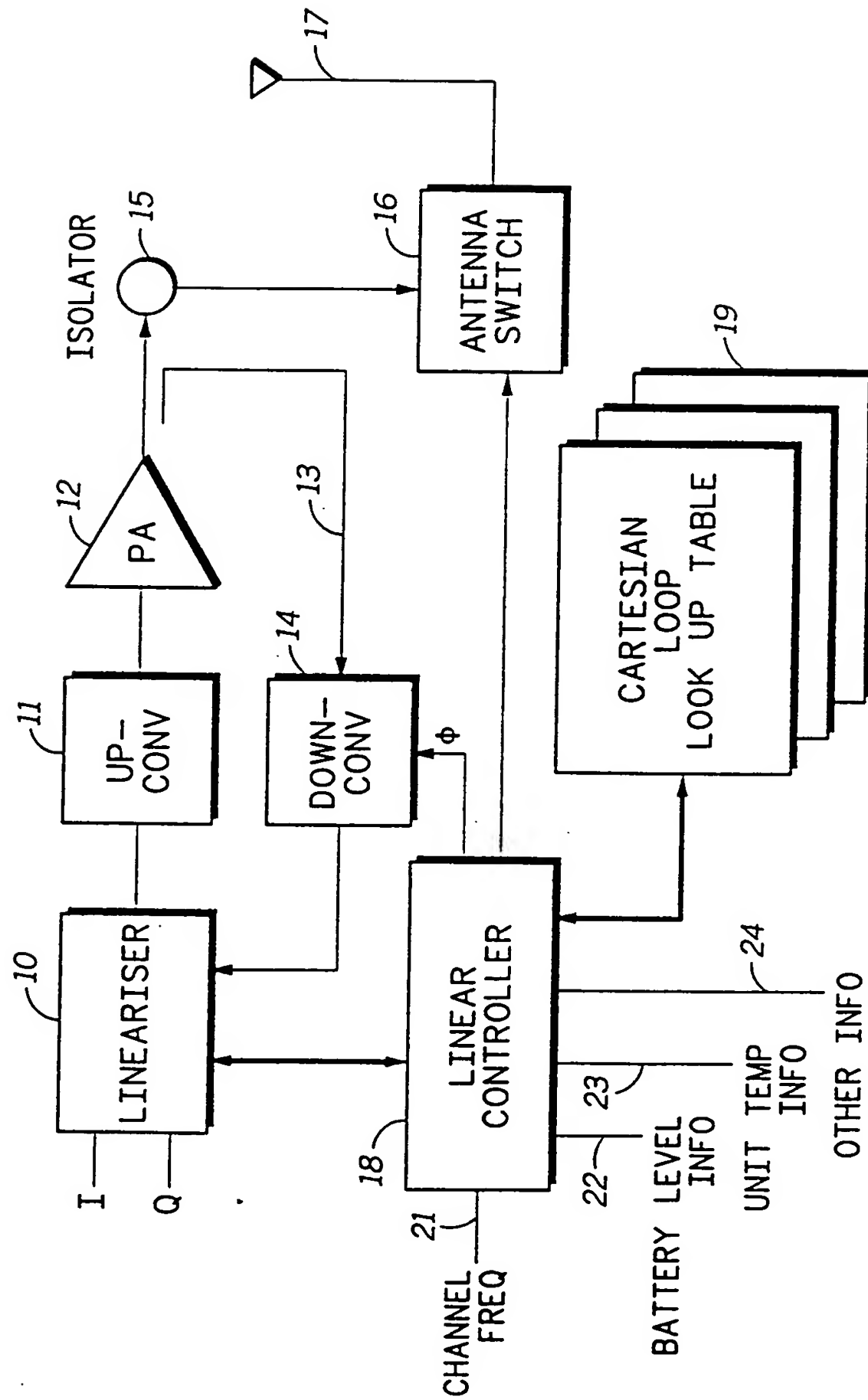for outputting a training sequence from the power amplifier;

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a feedback circuit for feeding the training sequence
output from the power amplifier back to the linearizer means
to adjust the linearizer means; and

means for switching the signal from the power amplifier
5   to the adjacent channel receiving means while the training
sequence is being output from the power amplifier.

11.   A radio according to claim 10 further comprising means
for transmitting a synchronization sequence for providing
10   timing information to a receiving radio and means for using
the synchronization sequence as a training sequence and
training to the synchronization sequence.
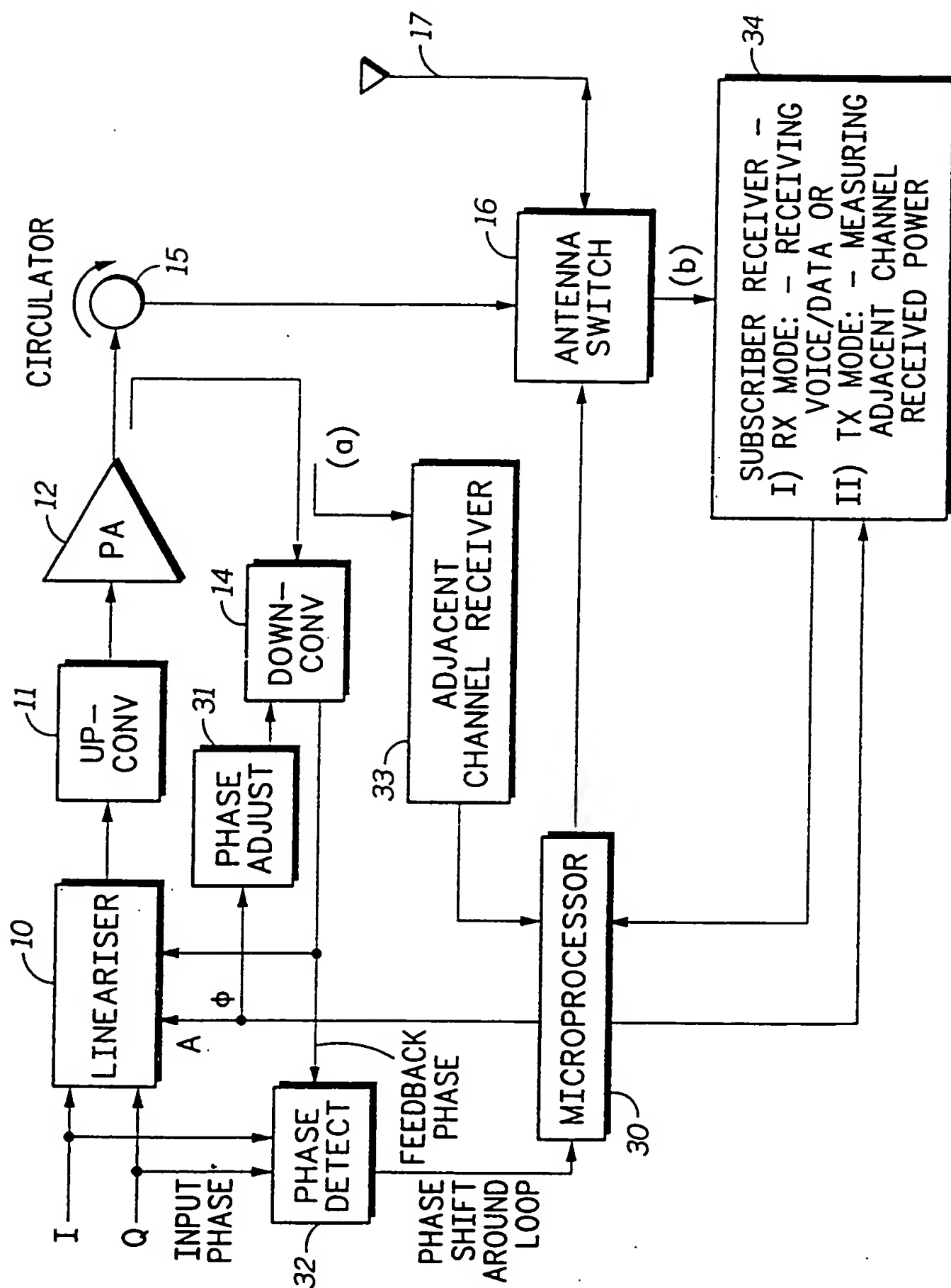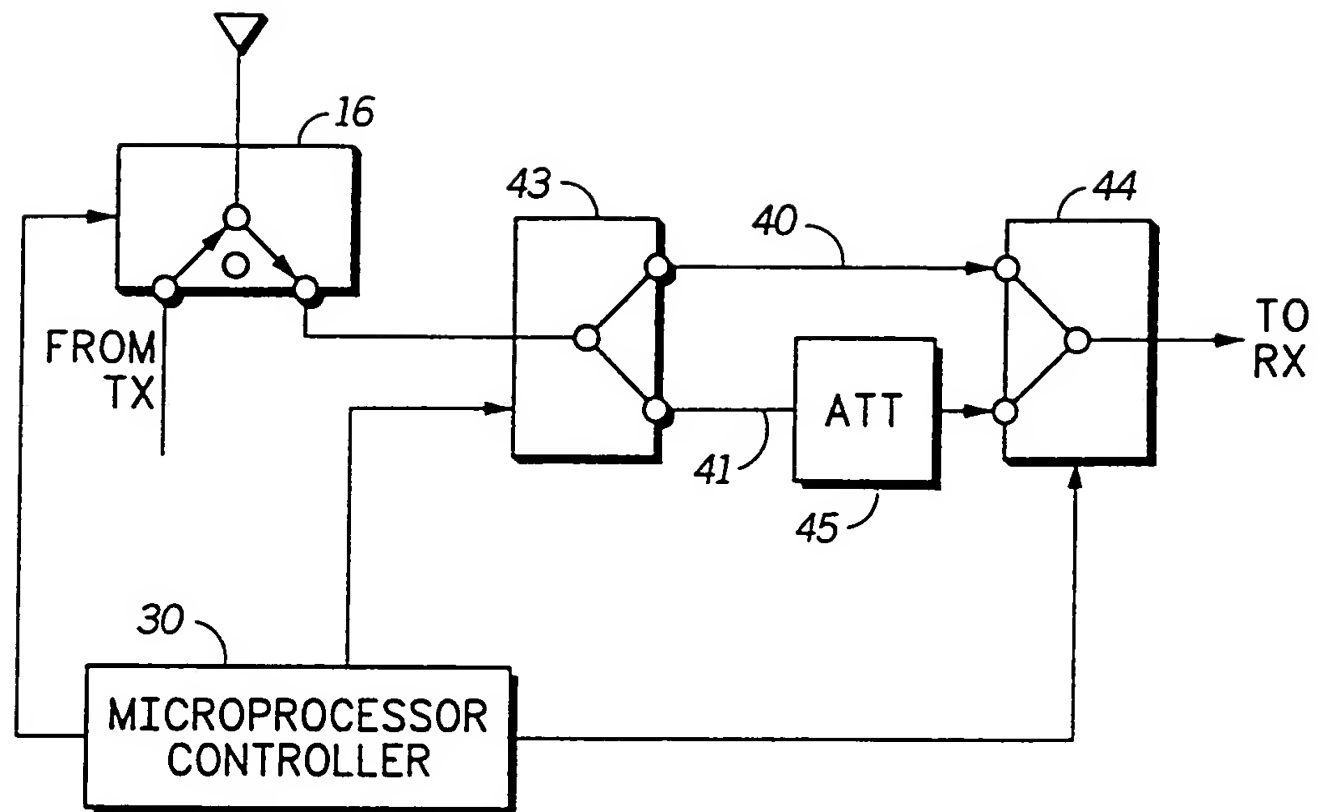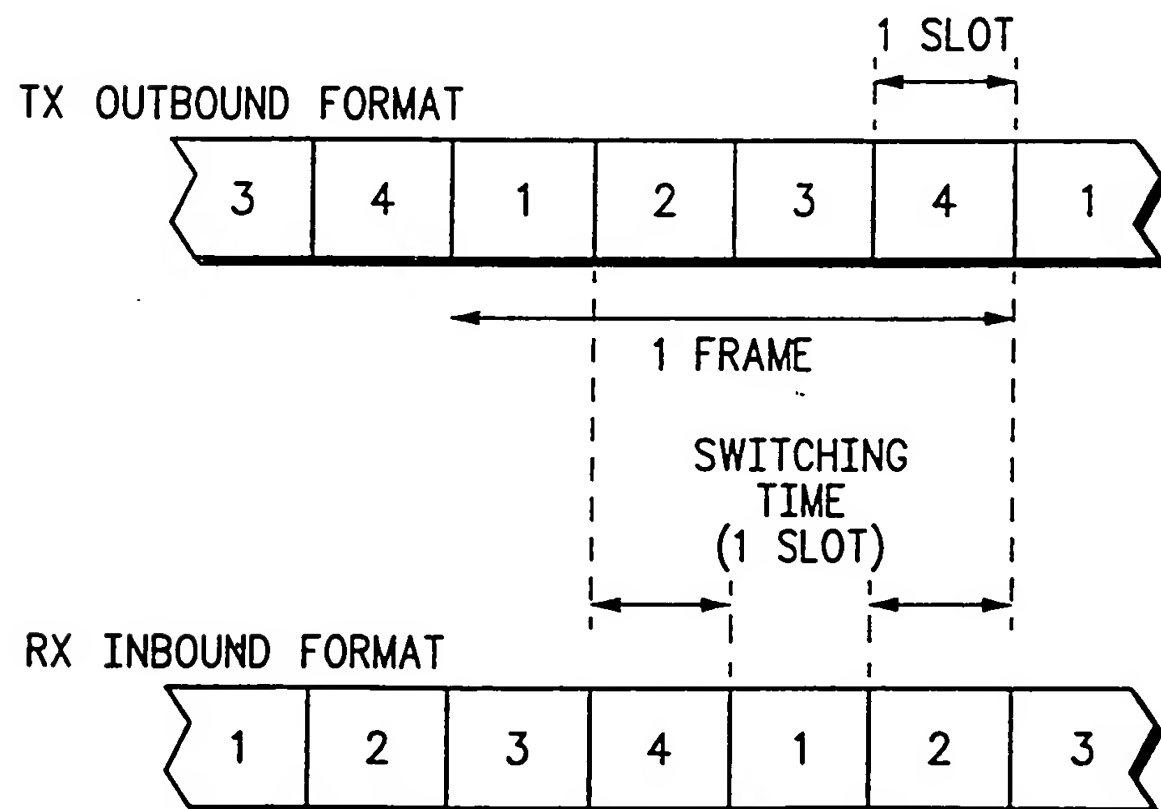
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LINEARISER BLOCK DIAGRAM *FIG.1*

FIG.2

FROM
TX

TO
RX

ATT

MICROPROCESSOR
CONTROLLER

FIG.3

1 SLOT

TX OUTBOUND FORMAT

| 3 | 4 | 1 | 2 | 3 | 4 | 1 |

1 FRAME

SWITCHING
TIME
(1 SLOT)

RX INBOUND FORMAT

| 1 | 2 | 3 | 4 | 1 | 2 | 3 |

FIG.4

I. CLASSIFICATION OF SUBJECT MATTER   (If several classification symbols apply, indicate all)[6]

According to International Patent Classification (IPC) or to both National Classification and IPC

Int.Cl. 5 H03F1/32

II. FIELDS SEARCHED

Minimum Documentation Searched[7]

Classification System	Classification Symbols
Int.Cl. 5	H03F ; H04L ; H04B

Documentation Searched other than Minimum Documentation
to the Extent that such Documents are Included in the Fields Searched[8]

III. DOCUMENTS CONSIDERED TO BE RELEVANT[9]

Category[°]	Citation of Document, [11] with indication, where appropriate, of the relevant passages [12]	Relevant to Claim No.[13]
Y	40TH IEEE VEHICULAR TECHNOLOGY CONFERENCE 9 May 1990, ORLANDO, FLORIDA pages 35 - 40 , XP203781 FAULKNER ET AL. 'Adaptive Linearisation Using Pre-distortion' see page 36, column 2, line 26 - page 37, column 1, line 36 see page 38, column 1, line 21; figure 1 ---	1-3
Y	IEE PROCEEDINGS-H vol. 138, no. 1, February 1991, STEVENAGE, HERTS., GB pages 9 - 12 , XP204587 'Memory controlled feedforward lineariser suitable for MMIC implementation' see page 1, line 10 - line 20; figure 3 ---	1-3
	-/--	

° Special categories of cited documents : [10]

"A" document defining the general state of the art which is not considered to be of particular relevance

"E" earlier document but published on or after the international filing date

"L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)

"O" document referring to an oral disclosure, use, exhibition or other means

"P" document published prior to the international filing date but later than the priority date claimed

"T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention

"X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step

"Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art.

"&" document member of the same patent family

IV. CERTIFICATION

Date of the Actual Completion of the International Search	Date of Mailing of this International Search Report
01 JUNE 1993	0 7. 06. 93

International Searching Authority	Signature of Authorized Officer
EUROPEAN PATENT OFFICE	WALDORFF U.

Form PCT/ISA/210 (second sheet) (January 1985)

III. DOCUMENTS CONSIDERED TO BE RELEVANT	(CONTINUED FROM THE SECOND SHEET)	
Category*	Citation of Document, with indication, where appropriate, of the relevant passages	Relevant to Claim No.
A	IEEE TRANSACTIONS ON VEHICULAR TECHNOLOGY vol. 39, no. 4, November 1990, NEW YORK, US pages 374 - 382 , XP173256 JAMES K. CAVERS 'Amplifier Linearization Using a Digital Predistorter with Fast Adaptation and Low Memory Requirements' see page 380, column 1, line 31 - page 382, column 1, line 6; figure 5 ---	1,3
A	IEEE GLOBAL TELECOMMUNICATIONS CONFERENCE vol. 1, 1 December 1986, HOUSTON, TX pages 126 - 132 K. SAM SHANMUGAN ET AL. 'An Adaptive Linearizer for 16-QAM Transmission over Non-linear Satellite Channels' see page 127, column 2, line 42 - line 60; figure 3 ---	6-8
X	41TH VEHICULAR TECHNOLOGY CONFERENCE 19 May 1991, ST. LOUIS, MO pages 753 - 758 , XP260272 S.P.STAPLETON ET AL. 'A New Technique for Adaptation og Linearizing Predistorters'	9
A	see page 753, column 1, line 1 - page 754, column 1, line 5 see page 756, column 1, line 12 - column 2, line 20; figure 2 ---	4
A	EP,A,0 253 482 (MARCONI INSTRUMENTS LIMITED) 20 January 1988 see page 2, line 3 - line 9 ---	4,9
A	US,A,5 066 923 (PAUL H. GAILUS) 19 November 1991 cited in the application see column 3, line 7 - line 33 see column 5, line 25 - line 35 -----	10,11

ANNEX TO THE INTERNATIONAL SEARCH REPORT
ON INTERNATIONAL PATENT APPLICATION NO.

EP   9300430
SA   70476

This annex lists the patent family members relating to the patent documents cited in the above-mentioned international search report.
The members are as contained in the European Patent Office EDP file on
The European Patent Office is in no way liable for these particulars which are merely given for the purpose of information.   01/06/9

Patent document cited in search report	Publication date	Patent family member(s)		Publication date
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		JP-A-	62299126	26-12-87
		US-A-	4810960	07-03-89
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For more details about this annex : see Official Journal of the European Patent Office, No. 12/82